

libcppa

An implementation of the actor model for C++

User Manual

libcppa version 0.5.2

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1 First Steps

To compile `libcppa`, you will need CMake, the Boost Library and a C++11 compiler. To get and compile the sources, open a terminal and type:

```
git clone git://github.com/Neverlord/libcppa.git
cd libcppa
./configure
make
make install [as root, optional]
```

It is recommended to run the unit tests as well:

```
make test
```

Please submit a bug report that includes (a) your compiler version, (b) your OS, and (c) the content of the file `build/Testing/Temporary/LastTest.log` if an error occurs.

1.1 Features Overview

- Lightweight, fast and efficient actor implementations
- Network transparent messaging
- Error handling based on Erlang's failure model
- Pattern matching for messages as internal DSL to ease development
- Thread-mapped actors and on-the-fly conversions for soft migration of existing applications
- Group communication based on Publish/Subscribe

1.2 Supported Compilers

- GCC ≥ 4.7
- Clang ≥ 3.2

1.3 Supported Operating Systems

- Linux
- Mac OS X
- *Note for MS Windows:* `libcppa` relies on C++11 features such as variadic templates. We will support this platform as soon as Microsoft's compiler implements all required C++11 features.

1.4 Hello World Example

```
#include <string>
#include <iostream>
#include "cppa/cppa.hpp"

using namespace cppa;

void echo_actor() {
    // wait for a message
    receive (
        // invoke this lambda expression if we receive a string
        on<std::string>() >> [](const std::string& what) {
            // prints "Hello World!"
            std::cout << what << std::endl;
            // replies "!dlroW olleH"
            reply(std::string(what.rbegin(), what.rend()));
        }
    );
}

int main() {
    // create a new actor that invokes the function echo_actor
    auto hello_actor = spawn(echo_actor);
    // send "Hello World!" to our new actor
    // note: libcppa converts string literals to std::string
    send(hello_actor, "Hello World!");
    // wait for a response and print it
    receive (
        on<std::string>() >> [](const std::string& what) {
            // prints "!dlroW olleH"
            std::cout << what << std::endl;
        }
    );
    // wait until all other actors we've spawned are done
    await_all_others_done();
    // done
    shutdown();
    return 0;
}
```

2 Copy-On-Write Tuples

The message passing implementation of `libcppa` uses tuples with call-by-value semantic. Hence, it is not necessary to declare message types, though, `libcppa` allows users to use user-defined types in messages (see Section 13.1). A call-by-value semantic would cause multiple copies of a tuple if it is send to multiple actors. To avoid unnecessary copying overhead, `libcppa` uses a copy-on-write tuple implementation. A tuple is implicitly shared between any number of actors, as long as all actors demand only read access. Whenever an actor demands write access, it has to copy the data first if more than one reference to it exist. Thus, race conditions cannot occur and each tuple is copied only if necessary.

The interface of `cow_tuple` strictly distinguishes between `const` and non-`const` access. The template function `get` returns an element as immutable value, while `get_ref` explicitly returns a mutable *reference* to the required value and detaches the tuple if needed. We do not provide a `const` overload for `get`, because this would cause to unintended, and thus unnecessary, copying overhead.

```
auto x1 = make_cow_tuple(1, 2, 3);           // cow_tuple<int, int, int>
auto x2 = x1;                               // cow_tuple<int, int, int>
assert(&get<0>(x1) == &get<0>(x2));          // point to the same data
get_ref<0>(x1) = 10;                         // detaches x1 from x2
//get<0>(x1) = 10;                          // compiler error
assert(get<0>(x1) == 10);                    // x1 is now {10, 2, 3}
assert(get<0>(x2) == 1);                     // x2 is still {1, 2, 3}
assert(&get<0>(x1) != &get<0>(x2));          // no longer the same
```

2.1 Dynamically Typed Tuples

The class `any_tuple` represents a tuple without static type information. All messages send between actors use this tuple type. The type information can be either explicitly accessed for each element or the original tuple, or a subtuple of it, can be restored using `tuple_cast`. Users of `libcppa` usually do not need to know about `any_tuple`, since it is used “behind the scenes”. However, `any_tuple` can be created from a `cow_tuple` or by using `make_any_tuple`, as shown below.

```
auto x1 = make_cow_tuple(1, 2, 3);           // cow_tuple<int, int, int>
any_tuple x2 = x1;                           // any_tuple
any_tuple x3 = make_cow_tuple(10, 20);       // any_tuple
auto x4 = make_any_tuple(42);                // any_tuple
```

2.2 Casting Tuples

The function `tuple_cast` restores static type information from an `any_tuple` object. It returns an option (see Section 14.1) for a `cow_tuple` of the requested types.

```
auto x1 = make_any_tuple(1, 2, 3);
auto x2_opt = tuple_cast<int, int, int>(x1);
assert(x2_opt.valid());
auto x2 = *x2_opt;
assert(get<0>(x2) == 1);
assert(get<1>(x2) == 2);
assert(get<2>(x2) == 3);
```

The function `tuple_cast` can be used with wildcards (see Section 3.4) to create a view to a subset of the original data. No elements are copied, unless the tuple becomes detached.

```
auto x1 = make_cow_tuple(1, 2, 3);
any_tuple x2 = x1;
auto x3_opt = tuple_cast<int, anything, int>(x2);
assert(x3_opt.valid());
auto x3 = *x3_opt;
assert(get<0>(x3) == 1);
assert(get<1>(x3) == 3);
assert(&get<0>(x3) == &get<0>(x1));
assert(&get<1>(x3) == &get<2>(x1));
```

3 Pattern Matching

C++ does not provide pattern matching facilities. A general pattern matching solution for arbitrary data structures would require a language extension. Hence, we decided to restrict our implementation to tuples, to be able to use an internal domain-specific language approach.

3.1 Basics

A match expression begins with a call to the function `on`, which returns an intermediate object providing the member function `when` and `operator>>`. The right-hand side of the operator denotes a callback, usually a lambda expression, that should be invoked if a tuple matches the types given to `on`, as shown in the example below.

```
on<int>() >> [] (int i) { /*...*/ }
on<int, float>() >> [] (int i, float f) { /*...*/ }
on<int, int, int>() >> [] (int a, int b, int c) { /*...*/ }
```

The result of `operator>>` is a partial function that is defined for the types given to `on`. A comma separated list of partial functions results in a single partial function that sequentially evaluates its subfunctions. At most one callback is invoked, since the evaluation stops at the first match.

```
auto fun = (
    on<int>() >> [] (int i) {
        // case1
    },
    on<int>() >> [] (int i) {
        // is never invoked, since case1 always matches first
    }
);
```

Note: A list of partial function definitions must be enclosed in brackets if assigned to a variable. Otherwise, the compiler assumes commas to separate variable definitions.

The function “`on`” can be used in two ways. Either with template parameters only or with function parameters only. The latter version deduces all types from its arguments and matches for both type and value. The template “`val`” can be used to match only the type of a parameter.

```
on(42) >> [] (int i) { assert(i == 42); }
on("hello world") >> [] () { /* ... */ }
on("print", val<std::string>) >> [] (const std::string& what) {
    // ...
}
```

Note: The given callback can have less arguments than given to the pattern. But it is only allowed to skip arguments from left to right.

```
on<int, float, double>() >> [] (double) { /*...*/ } // ok
on<int, float, double>() >> [] (float, double) { /*...*/ } // ok
on<int, float, double>() >> [] (int, float, double) { /*...*/ } // ok

on<int, float, double>() >> [] (int i) { /*...*/ } // compiler error
```


3.2 Atoms

Assume an actor provides a mathematical service for integers. It takes two arguments, performs a predefined operation and returns the result. It cannot determine an operation, such as multiply or add, by receiving two operands. Thus, the operation must be encoded into the message. The Erlang programming language introduced an approach to use non-numerical constants, so-called *atoms*, which have an unambiguous, special-purpose type and do not have the runtime overhead of string constants. Atoms are mapped to integer values at compile time in `libcppa`. This mapping is guaranteed to be collision-free but limits atom literals to ten characters and prohibits special characters. Legal characters are “_0-9A-Za-z” and the whitespace character. Atoms are created using the `constexpr` function `atom`, as the following example illustrates.

```
on<atom("add"), int, int>() >> [](int a, int b) { /*...*/ },
on<atom("multiply"), int, int>() >> [](int a, int b) { /*...*/ },
// ...
```

Note: The current implementation cannot enforce the restrictions at compile time, except for a length check. Each invalid character is mapped to the whitespace character, why the assertion `atom("!?") != atom("?!")` is not true. However, this issue will fade away after user-defined literals become available in mainstream compilers, because it is then possible to raise a compiler error for invalid characters.

3.3 Reducing Redundancy with “arg_match” and “on_arg_match”

Our previous example is quite verbose and redundant, since you have to type the types twice – as template parameter and as argument type for the lambda. To avoid such redundancy, `arg_match` can be used as last argument to the function `on`. This causes the compiler to deduce all further types from the signature of the given callback.

```
on<atom("add"), int, int>() >> [](int a, int b) { /*...*/ }
// is equal to:
on(atom("add"), arg_match) >> [](int a, int b) { /*...*/ }
```

Note that the second version does call `on` without template parameters. Furthermore, `arg_match` must be passed as last parameter. If all types should be deduced from the callback signature, `on_arg_match` can be used. It is equal to `on(arg_match)`.

```
on_arg_match >> [](const std::string& str) { /*...*/ }
```

3.4 Wildcards

The type `anything` can be used as wildcard to match any number of any types. A pattern created by `on<anything>()` or its alias `others()` is useful to define a default case. For patterns defined without template parameters, the `constexpr` value `any_vals` can be used as function argument. The constant `any_vals` is of type `anything` and is nothing but syntactic sugar for defining patterns.

```
on<int, anything>() >> [](int i) {
    // tuple with int as first element
},
on(any_vals, arg_match) >> [](int i) {
    // tuple with int as last element
    // "on(any_vals, arg_match)" is equal to "on(anything{}, arg_match)"
},
others() >> []() {
    // everything else (default handler)
    // "others()" is equal to "on<anything>()" and "on(any_vals)"
}
```

3.5 Guards

Guards can be used to constrain a given match statement by using placeholders, as the following example illustrates.

```
using namespace cppa::placeholders; // contains _x1 - _x9

on<int>().when(_x1 % 2 == 0) >> []() {
    // int is even
},
on<int>() >> []() {
    // int is odd
}
```

Guard expressions are a lazy evaluation technique. The placeholder `_x1` is substituted with the first value of a given tuple. All binary comparison and arithmetic operators are supported, as well as `&&` and `||`. In addition, there are two functions designed to be used in guard expressions: `gref` (“guard reference”) and `gcall` (“guard function call”). The function `gref` creates a reference wrapper. It is similar to `std::ref` but it is always `const` and “lazy”, i.e., evaluated when a tuple arrives. A few examples to illustrate some pitfalls:

```
int val = 42;

on<int>().when(_x1 == val)           // (1) matches if _x1 == 42
on<int>().when(_x1 == gref(val))     // (2) matches if _x1 == val
on<int>().when(_x1 == std::ref(val)) // (3) ok, because of placeholder
others().when(gref(val) == 42)      // (4) matches everything
                                   // as long as val == 42
others().when(std::ref(val) == 42)  // (5) compiler error
```

Statement (5) is evaluated immediately and returns a boolean, whereas statement (4) creates a valid guard expression. Thus, you should always use `gref` instead of `std::ref` to avoid errors.

The second function, `gcall`, encapsulates a function call. Its usage is similar to `std::bind`, but there is also a short version for unary functions: `gcall(fun, _x1)` is equal to `_x1(fun)`.

```
auto vec_sorted = [] (std::vector<int> const& vec) {
    return std::is_sorted(vec.begin(), vec.end());
};
```

```
on<std::vector<int>>().when(gcall(vec_sorted, _x1)) // is equal to:
on<std::vector<int>>().when(_x1(vec_sorted))
```

3.5.1 Placeholder Interface

```
template<int X>
struct guard_placeholder;
```

Member functions (`x` represents the value at runtime, `y` represents an iterable container)

<code>size()</code>	Returns <code>x.size()</code>
<code>empty()</code>	Returns <code>x.empty()</code>
<code>not_empty()</code>	Returns <code>!x.empty()</code>
<code>front()</code>	Returns an option (see Section 14.1) to <code>x.front()</code>
<code>in(y)</code>	Returns <code>true</code> if <code>y</code> contains <code>x</code> , <code>false</code> otherwise
<code>not_in(y)</code>	Returns <code>!in(y)</code>

3.5.2 Examples for Guard Expressions

```
using namespace std;
typedef vector<int> ivec;

vector<string> strings{"abc", "def"};

on<ivec>().when(_x1.front() == 0) >> [] (const ivec& v) {
    // note: we don't have to check whether _x1 is empty in our guard,
    //       because '_x1.front()' returns an option for a
    //       reference to the first element
    assert(v.size() >= 1);
    assert(v.front() == 0);
},
on<int>().when(_x1.in({10, 20, 30})) >> [] (int i) {
    assert(i == 10 || i == 20 || i == 30);
},
on<string>().when(_x1.not_in(strings)) >> [] (const string& str) {
    assert(str != "abc" && str != "def");
},
on<string>().when(_x1.size() == 10) >> [] (const string& str) {
    // ...
}
```

3.6 Projections and Extractors

Projections perform type conversions or extract data from a given input. If a callback expects an integer but the received message contains a string, a projection can be used to perform a type conversion on-the-fly. This conversion should be free of side-effects and, in particular, shall not throw exceptions, because a failed projection is not an error. A pattern simply does not match if a projection failed. Let us have a look at a simple example.

```
auto intproj = [](const string& str) -> option<int> {
    char* endptr = nullptr;
    int result = static_cast<int>(strtol(str.c_str(), &endptr, 10));
    if (endptr != nullptr && *endptr == '\\0') return result;
    return {};
};

auto fun = (
    on(intproj) >> [](int i) {
        // case 1, successfully converted a string
    },
    on_arg_match >> [](const string& str) {
        // case 2, str is not an integer
    }
);
```

The lambda `intproj` is a `string \Rightarrow int` projection, but note that it does not return an integer. It returns `option<int>`, because the projection is not guaranteed to always succeed. An empty `option` indicates, that a value does not have a valid mapping to an integer. A pattern does not match if a projection failed.

Note: Functors used as projection must take exactly one argument and must return a value. The types for the pattern are deduced from the functor's signature. If the functor returns an `option<T>`, then `T` is deduced.

4 Actors

`libcppa` provides three actor implementations, each covering a particular use case. The class `local_actor` is the base class for all implementations, except for (remote) proxy actors.

4.1 Local Actors

The class `local_actor` describes a local running actor. It provides a common interface for actor operations like trapping exit messages or finishing execution.

4.1.1 “Keyword” `self`

The `self` pointer is an essential ingredient of our design. It identifies the running actor similar to the implicit `this` pointer identifying an object within a member function. Unlike `this`, though, `self` is not limited to a particular scope. The `self` pointer is used implicitly, whenever an actor calls functions like `send` or `receive`, but can be accessed to use more advanced actor operations such as linking to another actor, e.g., by calling `self->link_to(other)`. The `self` pointer is convertible to `actor_ptr` and `local_actor*`, but it is neither copyable nor assignable. Thus, `auto s = self` will cause a compiler error, while `actor_ptr s = self` works as expected.

A thread that accesses `self` is converted on-the-fly to an actor if needed. Hence, “everything is an actor” in `libcppa`.

4.1.2 Interface

```
class local_actor;
```

Member functions

<code>quit(uint32_t reason = normal)</code>	Finishes execution of this actor
Observers	
<code>bool trap_exit()</code>	Checks whether this actor traps exit messages
<code>bool chaining()</code>	Checks whether this actor uses the “chained send” optimization (see Section 5.2)
<code>any_tuple last_dequeued()</code>	Returns the last message that was dequeued from the actor’s mailbox Note: Only set during callback invocation
<code>actor_ptr last_sender()</code>	Returns the sender of the last dequeued message Note₁: Only set during callback invocation Note₂: Used by the function <code>reply</code> (see Section 5.1)
Modifiers	
<code>void trap_exit(bool enabled)</code>	Enables or disables trapping of exit messages
<code>void chaining(bool enabled)</code>	Enables or disables chained send

4.2 Types of Actors

We have already shown the differences of context-switching and event-based actors in Section 6. Context-switching and event-based actors are scheduled cooperatively in a thread pool. Developers can opt-out of this cooperative scheduling by using thread-mapped actors.

4.2.1 Thread-Mapped Actors

This is the implicit type of all threads that were converted to actors implicitly. Furthermore, this type is used for actors created with `spawn<detached>`. It is recommended to use detached actors whenever an actor could starve other actors, e.g., by calling time-expensive, blocking system calls. Detached actors also could be used for actors that need to stay responsive, independent of the current work load. However, threads do not scale well. Hence, detached actors should be used only in small numbers for long-lived actors.

4.2.2 Context-Switching Actors

Context-switching actors have an own control flow and allow developers to spawn arbitrary functions as actors. The downside of context-switching actors is that each actor needs to allocate its own stack. This seriously impacts the performance for short-lived actors and is not applicable for large-scale actor systems. This implementations allows for an easy migration of previously threaded application, but a system should not contain more than a few hundred context-switching actors.

4.2.3 Event-Based Actors

This is the recommended implementation for most use cases. Event-based actors have a small memory footprint and are thus very lightweight. The behavior-based API makes it harder to nest receives, but this implementation clearly scales best. See Section 6.2 for a few examples.

5 Sending Messages

Messages can be sent by using either the function `send`, or `send_tuple`, or `operator<<`. The variadic template function `send` has the following signature.

```
template<typename... Args>
void send(actor_ptr whom, Args&&... what);
```

The variadic template pack `what...` is converted to a dynamically typed tuple (see Section 2.1) and then enqueued to the mailbox of `whom`. The following example shows two equal sends, one using `send` and the other using `operator<<`.

```
actor_ptr other = spawn(...);
send(other, 1, 2, 3);
other << make_any_tuple(1, 2, 3);
```

Using the function `send` is more compact, but does not have any other benefit. However, note that you should not use `send` if you already have an instance of `any_tuple`, because it creates a new tuple containing the old one.

```
actor_ptr other = spawn(...);
auto msg = make_any_tuple(1, 2, 3);
send(other, msg); // oops, creates a new tuple that contains msg
other << msg;    // ok
```

The function `send_tuple` is equal to `operator<<`. Choosing one or the other is merely a matter of personal preferences.

5.1 Replying to Messages

During callback invocation, `self->last_sender()` is set. This identifies the sender of the received message and is used implicitly by the functions `reply` and `reply_tuple`.

Using `reply(...)` is **not** equal to `send(self->last_sender(), ...)`. The function `send` always uses asynchronous message passing, whereas `reply` will send a synchronous response message if the received message was a synchronous request (see Section 7).

To delay a response, i.e., reply to a message after receiving another message, actors can use `self->make_response_handle()`. The functions `reply_to` and `reply_tuple_to` then can be used to reply to the original request, as shown in the example below.

```
class broker : public event_based_actor {
    // ...
    on("foo", arg_match) >> [=](const std::string& request) {
        auto hdl = make_response_handle();
        sync_send(master, atom("bar"), request).then(
            on_arg_match >> [=](const std::string& response) {
                reply_to(hdl, response);
            },
            after...
        );
    }
    // ...
};
```

In any case, do never reply than more than once. Additional (synchronous) response message will be ignored by the receiver.

5.2 Chaining Sends

Sending a message to a cooperatively scheduled actor usually causes the receiving actor to be put into the scheduler's job queue if it is currently blocked, i.e., is waiting for a new message. This job queue is accessed by worker threads. The *chaining* optimization does not cause the receiver to be put into the scheduler's job queue if it is currently blocked. The receiver is stored as successor of the currently running actor instead. Hence, the active worker thread does not need to access the job queue, which significantly speeds up execution. However, this optimization can be inefficient if an actor first sends a message and then starts computation.

```
void foo(actor_ptr other) {
    send(other, ...);
    very_long_computation();
    // ...
}

int main() {
    // ...
    auto a = spawn(...);
    auto b = spawn(foo, a);
    // ...
}
```

The example above illustrates an inefficient work flow. The actor `other` is marked as successor of the `foo` actor but its execution is delayed until `very_long_computation()` is done. In general, actors should follow the work flow `receive` \Rightarrow `compute` \Rightarrow `send results`. However, this optimization can be disabled by calling `self->chaining(false)` if an actor does not match this work flow.

```
void foo(actor_ptr other) {
    self->chaining(false);    // disable chaining optimization
    send(other, ...);        // not delayed by very_long_computation
    very_long_computation();
    // ...
}
```

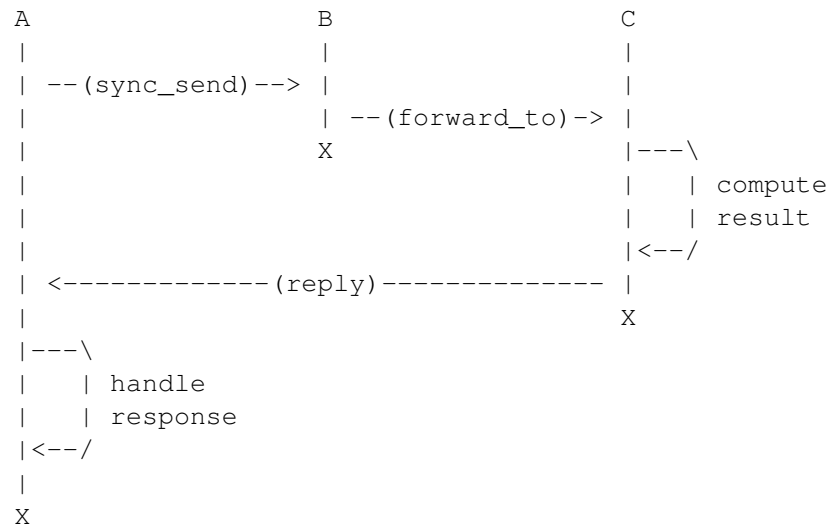
5.3 Delaying Messages

Messages can be delayed, e.g., to implement time-based polling strategies, by using one of the functions `delayed_send`, `delayed_send_tuple`, `delayed_reply`, or `delayed_reply_tuple`. The following example illustrates a polling strategy using `delayed_send`.

```
delayed_send(self, std::chrono::seconds(1), atom("poll"));
receive_loop (
    on(atom("poll")) >> []() {
        // poll a resource...
        // schedule next polling
        delayed_send(self, std::chrono::seconds(1), atom("poll"));
    }
);
```

5.4 Forwarding Messages

The function `forward_to` forwards the last dequeued message to an other actor. Forwarding a synchronous message will also transfer responsibility for the request, i.e., the receiver of the forwarded message can reply as usual and the original sender of the message will receive the response. The following diagram illustrates forwarding of a synchronous message from actor B to actor C.



The forwarding is completely transparent to actor C, since it will see actor A as sender of the message. However, actor A will see actor C as sender of the response message instead of actor B and thus could recognize the forwarding by evaluating `self->last_sender()`.

6 Receiving Messages

Event-based actors differ in receiving messages from context-switching and thread-mapped actors: the former define their behavior as a message handler that is invoked whenever a new message arrives in the actor's mailbox, whereas the latter use an explicit receive function. The current *behavior* of an actor is its response to the *next* incoming message and includes (a) sending messages to other actors, (b) creation of more actors, and (c) setting a new behavior.

6.1 Blocking API for Context-Switching and Thread-Mapped Actors

The function `receive` sequentially iterates over all elements in the mailbox beginning with the first. It takes a partial function that is applied to the elements in the mailbox until an element was matched by the partial function. An actor calling `receive` is blocked until it successfully dequeued a message from its mailbox or an optional timeout occurs.

```
receive (  
    on<int>().when(_x1 > 0) >> // ...  
);
```

The code snippet above illustrates the use of `receive`. Note that the partial function passed to `receive` is a temporary object at runtime. Hence, using `receive` inside a loop would cause creation of a new partial function on each iteration. `libcppa` provides three predefined receive loops to provide a more efficient but yet convenient way of defining receive loops.

//DON'T

```
for (;;) {
    receive (
        // ...
    );
}
```

```
std::vector<int> results;
for (size_t i = 0; i < 10; ++i) {
    receive (
        on<int>() >> [&](int value) {
            results.push_back(value);
        }
    );
}
```

```
size_t received = 0;
do {
    receive (
        others() >> [&]() {
            ++received;
        }
    );
} while (received < 10);
```

//DO

```
receive_loop (
    // ...
);
```

```
std::vector<int> results;
size_t i = 0;
receive_for(i, 10) (
    on<int>() >> [&](int value) {
        results.push_back(value);
    }
);
```

```
size_t received = 0;
do_receive (
    others() >> [&]() {
        ++received;
    }
).until(gref(received) >= 10);
```

The examples above illustrate the correct usage of the three loops `receive_loop`, `receive_for` and `do_receive(...).until`. It is possible to nest receives and receive loops.

```
receive_loop (
    on<int>() >> [] (int value1) {
        receive (
            on<float>() >> [&](float value2) {
                cout << value1 << " ==> " << value2 << endl;
            }
        );
    }
);
```

6.2 Event-Based API

An event-based actor uses `become` to set its behavior. The given behavior is then executed until it is replaced by another call to `become` or the actor finishes execution. A subtype of `event_based_actor` must implement the pure virtual member function `init`. An implementation of `init` shall set an initial behavior by using `become`.

```
class printer : public event_based_actor {
    void init() {
        become (
            others() >> []() {
                cout << to_string(self->last_received()) << endl;
            }
        );
    }
};
```

6.2.1 State-Based Actors

Another way to implement event-based actors is provided by the class `sb_actor` (“State-Based Actor”). This base class calls `become(init_state)` in its `init` member function. Hence, a subclass must only provide a member of type `behavior` named `init_state`.

```
struct printer : sb_actor<printer> {
    behavior init_state = (
        others() >> []() {
            cout << to_string(self->last_received()) << endl;
        }
    );
};
```

Note that `sb_actor` uses the Curiously Recurring Template Pattern. Thus, the derived class must be given as template parameter. This technique allows `sb_actor` to access the `init_state` member of a derived class.

The following example illustrates a more advanced state-based actor that implements a stack with a fixed maximum number of elements. Note that this example uses non-static member initialization and thus might not compile with some compilers.

```
class fixed_stack : public sb_actor<fixed_stack> {

    // grant access to the private init_state member
    friend class sb_actor<fixed_stack>;

    static constexpr size_t max_size = 10;

    std::vector<int> data;

    behavior empty = (
        on(atom("push"), arg_match) >> [=] (int what) {
            data.push_back(what);
            become(filled);
        },
        on(atom("pop")) >> [=] () {
            reply(atom("failure"));
        }
    );

    behavior filled = (
        on(atom("push"), arg_match) >> [=] (int what) {
            data.push_back(what);
            if (data.size() == max_size)
                become(full);
        },
        on(atom("pop")) >> [=] () {
            reply(atom("ok"), data.back());
            data.pop_back();
            if (data.empty())
                become(empty);
        }
    );

    behavior full = (
        on(atom("push"), arg_match) >> [=] (int) { },
        on(atom("pop")) >> [=] () {
            reply(atom("ok"), data.back());
            data.pop_back();
            become(filled);
        }
    );

    behavior& init_state = empty;

};
```

6.2.2 Nesting Receives Using `become/unbecome`

Nesting receives in an event-based actor is slightly more difficult compared to context-switching or thread-mapped actors, since `become` does not block. An actor has to set a new behavior calling `become` with the `keep_behavior` policy to wait for the required message and then return to the previous behavior by using `unbecome`, as shown in the example below.

```
// receives {int, float} sequences
struct testee : event_based_actor {
    void init() {
        become (
            on<int>() >> [=](int value1) {
                become (
                    // the keep_behavior policy stores the current behavior
                    // on the behavior stack to be able to return to this
                    // behavior later on by calling unbecome()
                    keep_behavior,
                    on<float>() >> [=](float value2) {
                        cout << value1 << " => " << value2 << endl;
                        // restore previous behavior
                        unbecome();
                    }
                );
            }
        );
    }
};
```

An event-based actor finishes execution with normal exit reason if the behavior stack is empty after calling `unbecome`. The default policy of `become` is `discard_behavior` that causes an actor to override its current behavior. The policy flag must be the first argument of `become`.

6.2.3 Using a Factory to Define Event-Based Actors

The previously introduced ways to define event-based actors always required a class definition. A factory provides an ad-hoc way to define event-based actors using lambda expressions or other functors. The factory `factory::event_based` takes a functor that is used as `event_based_actor::init` implementation. Hence, the functor should call `become` to set an initial behavior. Note that you have to call `self->become`, since `become` is not available via the `this` pointer.

Though `event_based_actor::init` has zero arguments, the functor can take any number of pointer arguments. The factory then creates an actor with a member variable for each of those arguments and calls the functor with pointers to the actor's member variables. The member variables can be initialized with user-defined values passed to the `spawn` member function of the created factory, as shown in the following example.

```
auto f = factory::event_based([](std::string* name) {
    self->become (
        on(atom("get_name")) >> [name]() {
            reply(atom("name"), *name);
        }
    );
});
auto a1 = f.spawn("alice");
auto a2 = f.spawn("bob");
auto a3 = f.spawn(); // a3 has an empty name
```


6.3 Timeouts

During receive, an actor is blocked until it dequeues a message from its mailbox that matches the given pattern. If no such message ever arrives, the actor is blocked forever. This might be desirable if the actor only provides a service and should not do anything else. But often, we need to be able to recover if an expected messages does not arrive within a certain time period. The following examples illustrates the usage of `after` to define a timeout.

```
#include <chrono>
#include <iostream>

using std::cout;
using std::cerr;
using std::endl;

receive(
  on_arg_match >> [] (int i) { /* ... */ },
  on_arg_match >> [] (float i) { /* ... */ },
  others() >> [] () { /* ... */ },
  after(std::chrono::seconds(10)) >> [] () {
    cerr << "received nothing within 10 seconds..." << endl;
    // ...
  }
);

receive(
  after(std::chrono::milliseconds(50)) >> [] () {
    cerr << "slept for 50ms" << endl;
  }
);

receive(
  on_arg_match >> [] (int i) {
    cout << "found: " << i << endl;
  },
  after(std::chrono::seconds(0)) >> [] () {
    cout << "no integer found in mailbox" << endl;
  }
);
```

Callbacks given as timeout handler must have zero arguments. Any number of patterns can precede the timeout definition, but “after” must always be the final statement. Using a zero-duration timeout causes `receive` to not block.

`libcppa` supports `minutes`, `seconds`, `milliseconds` and `microseconds`. However, note that the precision depends on the operating system and your local work load. Thus, you should not depend on a certain clock resolution.

7 Synchronous Communication

`libcppa` uses a future-based API for synchronous communication. The functions `sync_send` and `sync_send_tuple` send synchronous request messages to the receiver and return a future to the response message. Note that the returned future is *actor-local*, i.e., only the actor that has send the corresponding request message is able to receive the response identified by such a future.

```
template<typename... Args>
message_future sync_send(actor_ptr whom, Args&&... what);

message_future sync_send_tuple(actor_ptr whom, any_tuple what);
```

A synchronous message is sent to the receiving actor's mailbox like any other asynchronous message. The response message, on the other hand, is treated separately.

Note: the runtime system will automatically reply with an empty message if the receiving actor did not respond to a received synchronous response message by using the function `reply`.

7.1 Receive Response Messages

The functions `receive_response` and `handle_response` can be used to receive response messages, as shown in the following example.

```
// an actor that replies with a string to atom("get")
auto testee = spawn<testee_impl>();

// "receive_response" usage example (blocking API)
auto future = sync_send(testee, atom("get"));
receive_response (future) (
    on_arg_match >> [&](const std::string& str) {
        // handle str
    },
    after(std::chrono::seconds(30)) >> [&]() {
        // handle error
    }
);

// "handle_response" usage example (event-based API)
auto future = sync_send(testee, atom("get"));
handle_response (future) (
    on_arg_match >> [=](const std::string& str) {
        // handle str
    },
    after(std::chrono::seconds(30)) >> [=]() {
        // handle error
    }
);
```

The function `receive_response` is similar to `receive`, i.e., it blocks the calling actor until either a response message was received or a timeout occurred.

Similar to `become`, the function `handle_response` is part of the event-based API and is used as “one-shot handler” to respond to a given future. The behavior passed to `handle_response` is executed *once* and the actor automatically returns to its previous behavior afterwards. It is possible to “stack” multiple `handle_response` calls. Each response handler is executed once and then automatically discarded.

In both cases, the behavior definition of the response handler requires a timeout.

7.2 Using `message_future`’s Member Functions to Receive a Response

Often, an actor sends a synchronous message and then wants to wait for the response. In this case, using either `handle_response` or `receive_response` is quite verbose. Therefore, `message_future` provides the two member functions `then` and `await`. Using `then` is equal to using `handle_response`, whereas `await` corresponds to `receive_response`, as illustrated by the following example.

```
// an actor that replies with a string to atom("get")
auto testee = spawn<testee_impl>();

// receive response by using "await" (blocking API)
sync_send(testee, atom("get")).await(
    on_arg_match >> [&](const std::string& str) {
        // handle str
    },
    after(std::chrono::seconds(30)) >> [&]() {
        // handle error
    }
);

// set response handler by using "then" (event-based API)
sync_send(testee, atom("get")).then(
    on_arg_match >> [=](const std::string& str) {
        // handle str
    },
    after(std::chrono::seconds(30)) >> [=]() {
        // handle error
    }
);
```

8 Management

`libcppa` adapts Erlang's well-established fault propagation model. It allows to build actor subsystem in which either all actors are alive or have collectively failed.

8.1 Links

Linked actors monitor each other. An actor sends an exit message to all of its links as part of its termination. The default behavior for actors receiving such an exit message is to die for the same reason, if the exit reason is non-normal. Actors can *trap* exit messages to handle them manually.

```
auto worker = spawn(...);
// receive exit messages as regular messages
self->trap_exit(true);
// monitor spawned actor
self->link_to(worker);
// wait until worker exited
receive (
    on(atom("EXIT"), exit_reason::normal) >> []() {
        // worker finished computation
    },
    on(atom("EXIT"), arg_match) >> [](std::uint32_t reason) {
        // worker died unexpectedly
    }
);
```

8.2 Monitors

A monitor observes the lifetime of an actor. Monitored actors send a down message to all monitors as part of their termination. Unlike exit messages, down messages are always treated like any other ordinary message.

```
auto worker = spawn(...);
// monitor spawned actor
self->monitor(worker);
// wait until worker exited
receive (
    on(atom("DOWN"), exit_reason::normal) >> []() {
        // worker finished computation
    },
    on(atom("DOWN"), arg_match) >> [](std::uint32_t reason) {
        // worker died unexpectedly
    }
);
```

Monitors are redundant. Hence, actors will receive one down message for each monitor.

8.3 Error Codes

All error codes are defined in the namespace `cppa::exit_reason`.

<code>normal</code>	<code>1</code>	Actor finished execution without error
<code>unhandled_exception</code>	<code>2</code>	Actor was killed due to an unhandled exception
<code>unallowed_function_call</code>	<code>3</code>	Indicates that an event-based actor tried to use blocking receive calls
<code>remote_link_unreachable</code>	<code>257</code>	Indicates that a remote actor became unreachable, e.g., due to connection error
<code>user_defined</code>	<code>65536</code>	Minimum value for user-defined exit codes

8.4 Attach Cleanup Code to an Actor

Actors can attach cleanup code to other actors. This code is executed immediately if the actor has already exited. Keep in mind that `self` refers to the currently running actor. Thus, `self` refers to the terminating actor and not to the actor that attached a functor to it.

```
auto worker = spawn(...);
actor_ptr observer = self;
// "monitor" spawned actor
worker->attach_functor([observer](std::uint32_t reason) {
    // this callback is invoked from worker => self == worker
    send(observer, atom("DONE"));
});
// wait until worker exited
receive (
    on(atom("DONE")) >> []() {
        // worker terminated
    }
);
```

Note: It is possible to attach code to remote actors, but the cleanup code will run on the local machine.

9 Spawning Actors

Actors are created using the function `spawn`. The arguments passed to `spawn` depend on the actor's implementation.

9.1 Create Actors from Functors

The recommended way to implement both context-switching and thread-mapped actors is to use functors, e.g., a free function or lambda expression. The arguments to the functor are passed to `spawn` as additional arguments. The optional `scheduling_hint` template parameter of `spawn` decides whether an actor should run in its own thread or use context-switching. The flag `detached` causes `spawn` to create a thread-mapped actor, whereas `scheduled`, the default flag, causes it to create a context-switching actor. The function `spawn` provides a quite similar usage as `std::thread`, as shown in the examples below.

```
#include "cppa/cppa.hpp"

using namespace cppa;

void fun1();
void fun2(int arg1, std::string arg2);

int main() {
    // spawn context-switching actors
    auto a1 = spawn(fun1); // equal to spawn<scheduled>(fun1)
    auto a2 = spawn(fun2, 42, "hello actor");
    auto a3 = spawn<scheduled>(fun2, 42, "hello actor");
    auto a4 = spawn([]() { /* ... */ }); // spawn a lambda expression
    auto a5 = spawn([](int) { /* ... */ }, 42);
    // spawn thread-mapped actors
    auto a6 = spawn<detached>(fun1);
    auto a7 = spawn<detached>([]() { /* ... */ });
    auto a8 = spawn<detached>(fun2, 0, "zero");
    // ...
}
```

Though it is possible to subtype `context_switching_actor` to implement a class-based actor using context-switching, it is not recommended. In general, context-switching and thread-mapped actors are intended to ease migration of existing applications or to implement managing actors on-the-fly using lambda expressions. Class-based actors should be a subtype of `event_based_actor`, since this is the recommended actor implementation of `libcoppa`.

Note: `spawn(fun, arg0, ...)` is *not* the same as `spawn(std::bind(fun, arg0, ...))`! For example, a call to `spawn(fun, self, ...)` will pass a pointer to the calling actor to the newly created actor, as expected, whereas `spawn(std::bind(fun, self, ...))` wraps the type of `self` into the function wrapper and evaluates `self` on function invocation. Thus, the actor will end up having a pointer to itself rather than a pointer to the actor that created it.

9.2 Create Class-Based Actors

Spawning class-based actors is straightforward and uses the function `spawn` as well. The template parameter is the implementing class rather than a `scheduling_hint`, since class-based actors are always scheduled. All arguments are forwarded to the constructor, as shown in the following example.

```
#include "cppa/cppa.hpp"

using namespace cppa;

class my_actor1 : public event_based_actor { /* ... */ };

class my_actor2 : public sb_actor<my_actor2> {
    /* ... */
public:
    my_actor2(int value1, float value 2) {
        // ...
    }
};

int main() {
    auto a1 = spawn<my_actor1>();
    auto a2 = spawn<my_actor2>(1, 2.0f);
    // ...
}
```

For spawning event-based actors without implementing an own class see Section 6.2.3. To spawn actors as members of a group see Section 11.3.

10 Network Transparency

All actor operations as well as sending messages are network transparent. Remote actors are represented by actor proxies that forward all messages.

10.1 Publishing of Actors

```
void publish(actor_ptr whom, std::uint16_t port, const char* addr = 0)
```

The function `publish` binds an actor to a given port. It throws `network_error` if socket related errors occur or `bind_failure` if the specified port is already in use. The optional `addr` parameter can be used to listen only to the given IP address. Otherwise, the actor accepts all incoming connections (`INADDR_ANY`).

```
publish(self, 4242);
receive_loop (
    on(atom("ping"), arg_match) >> [](int i) {
        reply(atom("pong"), i);
    }
);
```

10.2 Connecting to Remote Actors

```
actor_ptr remote_actor(const char* host, std::uint16_t port)
```

The function `remote_actor` connects to the actor at given host and port. A `network_error` is thrown if the connection failed.

```
auto pong = remote_actor("localhost", 4242);
send(pong, atom("ping"), 0);
bool done = false;
do_receive (
    on(atom("pong"), 10) >> [&]() {
        done = true;
    },
    on<atom("pong"), int>() >> [](int i) {
        reply(atom("ping"), i+1);
    }
).until(gref(done));
```


11 Group Communication

`libcppa` supports publish/subscribe-based group communication. Actors can join and leave groups and send messages to groups.

```
std::string group_module = ...;
std::string group_id = ...;
auto grp = group::get(group_module, group_id);
self->join(grp);
send(grp, atom("test"));
self->leave(grp);
```

11.1 Anonymous Groups

Groups created on-the-fly with `group::anonymous()` can be used to coordinate a set of workers. Each call to `group::anonymous()` returns a new group instance.

11.2 Local Groups

The `"local"` group module creates groups for in-process communication. For example, a group for GUI related events could be identified by `group::get("local", "GUI events")`. The group ID `"GUI events"` uniquely identifies a singleton group instance of the module `"local"`.

11.3 Spawn Actors in Groups

The function `spawn_in_group` can be used to create actors as members of a group. The function causes the newly created actors to call `self->join(...)` immediately and before `spawn_in_group` returns. The usage of `spawn_in_group` is equal to `spawn`, except for an additional group argument. The group handle is always the first argument, as shown in the examples below.

```
void fun1();
void fun2(int, float);
class my_actor1 : event_based_actor { /* ... */ };
class my_actor2 : event_based_actor {
    // ...
    my_actor2(const std::string& str) { /* ... */ }
};
// ...
auto grp = group::get(...);
auto a1 = spawn_in_group(grp, fun1);
auto a2 = spawn_in_group(grp, fun2, 1, 2.0f);
auto a3 = spawn_in_group<my_actor1>(grp);
auto a4 = spawn_in_group<my_actor2>(grp, "hello my_actor2!");
```

12 Common Pitfalls

12.1 Event-Based API

- The functions `become` and `handle_response` do not block, i.e., always return immediately. Thus, you should *always* capture by value in event-based actors, because all references on the stack will cause undefined behavior if a lambda is executed.

12.2 Mixing Event-Based and Blocking API

- Blocking `libcppa` function such as `receive` will **throw an exception** if accessed from an event-based actor. To catch as many errors as possible at compile-time, `libcppa` will produce an error if `receive` is called and the `this` pointer is set and points to an event-based actor.
- Context-switching and thread-mapped actors *can* use the `become` API, **but** they should use it either exclusively or not at all. Whenever a non-event-based actor calls `become()` for the first time, it will create a behavior stack and execute it until the behavior stack is empty. Thus, the *initial* `become` *blocks* until the behavior stack is empty, whereas all subsequent calls to `become` will return immediately. Related functions, e.g., `sync_send(...).then(...)`, behave the same, as they manipulate the behavior as well.

12.3 Synchronous Messages

- `send(self->last_sender(), ...)` is **not** equal to `reply(...)`. The two functions `receive_response` and `handle_response` will only recognize messages send via either `reply` or `reply_tuple`.
- A future returned by `sync_send` represents *exactly one* response message. Therefore, it is not possible to receive more than one response message. Calling `reply` more than once will result in lost messages and calling `handle_response` or `receive_response` more than once on a future will throw an exception.
- The future returned by `sync_send` is bound to the calling actor. It is not possible to transfer such a future to another actor. Calling `receive_response` or `handle_response` for a future bound to another actor is undefined behavior.

12.4 Sending Messages

- `send(whom, ...)` is syntactic sugar for `whom << make_any_tuple(...)`. Hence, a message sent via `send(whom, self->last_dequeued())` will not yield the expected result, since it wraps `self->last_dequeued()` into another `any_tuple` instance. The correct way of forwarding messages is `self->forward_to(whom)`.

12.5 Sharing

- It is strongly recommended to **not** share states between actors. In particular, no actor shall ever access member variables or member functions of another actor. Accessing shared memory segments concurrently can cause undefined behavior that is incredibly hard to find and debug. However, sharing *data* between actors is fine, as long as the data is *immutable* and all actors access the data only via smart pointers such as `std::shared_ptr`. Nevertheless, the recommended way of sharing informations is message passing. Sending data to multiple actors does *not* result in copying the data several times. Read Section 2 to learn more about `libcoppa`'s copy-on-write optimization for tuples.

13 Platform-Independent Type System

`libcppa` provides a fully network transparent communication between actors. Thus, `libcppa` needs to serialize and deserialize messages. Unfortunately, this is not possible using the RTTI system of C++. `libcppa` uses its own RTTI based on the class `uniform_type_info`, since it is not possible to extend `std::type_info`.

Unlike `std::type_info::name()`, `uniform_type_info::name()` is guaranteed to return the same name on all supported platforms. Furthermore, it allows to create an instance of a type by name.

```
// creates a signed, 32 bit integer
cppa::object i = cppa::uniform_typeid<int>()->create();
```

However, you should rarely if ever need to use `object` or `uniform_type_info`.

13.1 User-Defined Data Types in Messages

All user-defined types must be explicitly “announced” so that `libcppa` can (de)serialize them correctly, as shown in the example below.

```
#include "cppa/cppa.hpp"
using namespace cppa;

struct foo { int a; int b; };

int main() {
    announce<foo>(&foo::a, &foo::b);
    send(self, foo{1,2});
    return 0;
}
```

Without the `announce` function call, the example program would terminate with an exception, because `libcppa` rejects all types without available runtime type information.

`announce()` takes the class as template parameter and pointers to all members (or getter/setter pairs) as arguments. This works for all primitive data types and STL compliant containers. See the announce examples 1 – 4 of the standard distribution for more details.

Obviously, there are limitations. You have to implement `serialize/deserialize` by yourself if your class does implement an unsupported data structure. See `announce_example_5.cpp` in the examples folder.

14 Appendix

14.1 Class `option`

Defined in header `"cppa/option.hpp"`.

```
template<typename T>
class option;
```

Represents an optional value.

Member types

Member type	Definition
type	T

Member functions

<code>option()</code>	Constructs an empty option
<code>option(T value)</code>	Initializes <code>this</code> with <code>value</code>
<code>option(const option&)</code> <code>option(option&&)</code>	Copy/move construction
<code>option& operator=(const option&)</code> <code>option& operator=(option&&)</code>	Copy/move assignment

Observers

<code>bool valid()</code> <code>explicit operator bool()</code>	Returns <code>true</code> if <code>this</code> has a value
<code>bool empty()</code> <code>bool operator!()</code>	Returns <code>true</code> if <code>this</code> does not has a value
<code>const T& get()</code> <code>const T& operator*()</code>	Access stored value
<code>const T& get_or_else(const T& x)</code>	Returns <code>get()</code> if valid, <code>x</code> otherwise

Modifiers

<code>T& get()</code> <code>T& operator*()</code>	Access stored value
--	---------------------